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Solution to Exercise 2.3.1. Solution to Exercise 2.6.1. In the first case, order does not matter; in the second it does. "Delay" means  $t \rightarrow t - \tau$ . "Time-reverse" means  $t \rightarrow -t$ . Case 1  $y(t) = Gx(t - \tau)$ , and the way we apply the gain and delay the signal gives the same result. Case 2 Time-reverse then delay:  $y(t) = x(-(t - \tau)) = x(-t + \tau)$ .

### **Solutions to Exercises in Chapter 2 | Open Textbooks for ...**

McClellan, Schafer, and Yoder, DSP First, ISBN 0-13-065562-7. Prentice Hall, Upper Saddle River, NJ 07458. © 2016 Pearson Education, Inc. Home

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The result is most easily found in the spectrum's formula: the power in the signal-related part of  $x(t)$  is half the power of the signal  $s(t)$ . Solution to Exercise 4.9.1 The inverse transform of the frequency response is Multiplying the frequency response by means subtract from the original signal its time-delayed version. response's time-domain version by  $\Delta$  results in  $RC e^{u(t - \Delta)}$ .

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directly from the organism including electrical, chemical, pressure etc. The second is concerned with all of the remainder of the signals that are generated as part of a biomechatronic process.

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Solution First we have to determine the specifications in the digital freq. domain. Passband:  $p = 2 \cdot 10 \cdot 44 \cdot 0.4545$  rad Stopband:  $S = 2 \cdot 11 \cdot 44 \cdot 0.5$  rad  
Therefore we choose the passband of the ideal filter as  $C = 1 \cdot 2 \cdot p = S = 21 \cdot 44 \cdot 0.477$ . We

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Chun-Yang Chen and P. P. Vaidyanathan, "MIMO Radar Space-Time Adaptive Processing and Signal Design," Chapter 6 in MIMO Radar Signal Processing, J. Li and P. Stoica, Wiley, 2008. P. P. Vaidyanathan and Piya Pal, "Coprime sampling and arrays in one and multiple dimensions", in Multiscale Signal Analysis and Modeling, Edited by X. A. Shen and A ...

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